

Show *all* of your work and *explain* your answers fully. There is a total of 100 possible points.
You may use Sage to row-reduce matrices and include the output in your answer as justification.

1. Consider the linear transformation T below. P_1 is the vector space of polynomials with degree at most 1, and M_{22} is the vector space of 2×2 matrices. (45 points)

$$T: M_{22} \rightarrow P_1, \quad T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = (a + 2b + 3c - 3d) + (3a - b + 2c + 5d)x$$

$$(a) \text{ Compute the kernel of } T, K(T). \quad T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = 0 = 0+0x \Rightarrow \begin{array}{l} a+2b+3c-3d=0 \\ 3a-b+2c+5d=0 \end{array}$$

~~Augmented matix~~ $\xrightarrow{\text{ref}} \left[\begin{array}{ccc|c} 1 & 0 & 1 & 1 \\ 0 & 1 & -2 & 0 \end{array}\right] \Rightarrow \begin{array}{l} a = -c-d \\ b = -c+2d \end{array} \Rightarrow \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} -c-d & -c+2d \\ c & d \end{bmatrix} =$

$$= c\begin{bmatrix} -1 & -1 \\ 1 & 0 \end{bmatrix} + d\begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} \text{ so } K(T) = \left\langle \left\{ \begin{bmatrix} -1 & -1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} \right\} \right\rangle$$

- (b) Is T injective? Why? If not, find two elements of the domain that T takes to the same element of the codomain.

No, Theorem KILT + $K(T) \neq \{0\}$

$$T\left(\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}\right) = 0+0x = T\left(\begin{bmatrix} -1 & -1 \\ 1 & 0 \end{bmatrix}\right)$$

Thm LTTZZ in kernel, see above

- (c) Compute the range of T , $R(T)$.

$$4 = \dim(M_{22}) = n(T) + r(T) = 2 + r(T) \Rightarrow r(T) = 2$$

So the range of T is a subspace of P_1 (which has dimension 2) that has dimension 2. So $R(T) = P_1$.

- (d) Is T surjective? Why? If not, find an element of the codomain with an empty preimage.

Yes, by Theorem RSLT, since $R(T) = P_1$.

- (e) Is T invertible? Why?

No. Theorem ILTIS requires T to be both

injective and surjective (T is not both). Or

$\dim(M_{22}) = 4 \neq 2 = \dim(P_1)$ and apply Theorem IVESD.

2. Consider the linear transformation S below, which is invertible (you may assume this). Find a formula for the outputs of the inverse linear transformation S^{-1} . P_1 is the vector space of polynomials with degree at most 1. (25 points)

$$S: P_1 \rightarrow \mathbb{C}^2, \quad S(a+bx) = \begin{bmatrix} 2a+5b \\ a+3b \end{bmatrix}$$

Compute pre-images of a basis for the codomain: $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$

$$S^{-1}\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right): \quad S(a+bx) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \Rightarrow \begin{array}{l} 2a+5b=1 \\ a+3b=0 \end{array} \Rightarrow \begin{array}{l} a=3 \\ b=-1 \end{array}$$

$$S^{-1}\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \{3-x\} \Rightarrow S^{-1}\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = 3-x$$

$$S^{-1}\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right): \quad S(a+bx) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \Rightarrow \begin{array}{l} 2a+5b=0 \\ a+3b=1 \end{array} \Rightarrow \begin{array}{l} a=-5 \\ b=2 \end{array}$$

$$S^{-1}\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \{-5+2x\} \Rightarrow S^{-1}\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = -5+2x$$

Then,

$$\begin{aligned} S^{-1}\left(\begin{bmatrix} r \\ s \end{bmatrix}\right) &= S^{-1}\left(r\begin{bmatrix} 1 \\ 0 \end{bmatrix} + s\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) \\ &= rS^{-1}\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) + sS^{-1}\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) \\ &= r(3-x) + s(-5+2x) \\ &= (3r-5s) + (-r+2s)x \end{aligned}$$

3. Prove that the function T below is a linear transformation. P_1 is the vector space of polynomials with degree at most 1. (15 points)

$$T: P_1 \rightarrow \mathbb{C}^2, \quad T(a+bx) = \begin{bmatrix} 3a-b \\ 4b \end{bmatrix}$$

$$\begin{aligned} ① \quad & T((a_1+b_1x)+(a_2+b_2x)) = T((a_1+a_2)+(b_1+b_2)x) \\ &= \begin{bmatrix} 3(a_1+a_2)-(b_1+b_2) \\ 4(b_1+b_2) \end{bmatrix} = \begin{bmatrix} (3a_1-b_1)+(3a_2-b_2) \\ 4b_1+4b_2 \end{bmatrix} \\ &= \begin{bmatrix} 3a_1-b_1 \\ 4b_1 \end{bmatrix} + \begin{bmatrix} 3a_2-b_2 \\ 4b_2 \end{bmatrix} = T(a_1+b_1x) + T(a_2+b_2x) \end{aligned}$$

$$\begin{aligned} ② \quad & T(\alpha(a+bx)) = T(\alpha a + (\alpha b)x) = \begin{bmatrix} 3(\alpha a) - \alpha b \\ 4(\alpha b) \end{bmatrix} \\ &= \begin{bmatrix} \alpha(3a-b) \\ \alpha(4b) \end{bmatrix} = \alpha \begin{bmatrix} 3a-b \\ 4b \end{bmatrix} = \alpha T(a+bx) \end{aligned}$$

4. Suppose that $S: U \rightarrow V$ is an invertible linear transformation. Then prove that S^{-1} has one of the two defining properties of a linear transformation (either property, your choice, for full credit). (15 points)

Choose $\alpha \in \mathbb{C}$, $\underline{v} \in V$. Because S is invertible,
 S must be surjective (Theorem ILTIS) so there exists
 $a \underline{u} \in U$ with $S(\underline{u}) = \underline{v}$ & equivalently, $S^{-1}(\underline{v}) = \underline{u}$.

$$\begin{aligned} \text{Then } \quad & S^{-1}(\alpha \underline{v}) = S^{-1}(\alpha S(\underline{u})) \\ &= S^{-1}(S(\alpha \underline{u})) \quad \stackrel{S \text{ is a linear transformation}}{=} \\ &= I_u(\alpha \underline{u}) \\ &= \alpha \underline{u} \\ &= \alpha S^{-1}(\underline{v}) \end{aligned}$$

which is the second defining property.