Name: Key

Show all of your work and explain your answers fully. There is a total of 100 possible points.

Partial credit is proportional to the quality of your explanation. You may use Sage to manipulate and row-reduce matrices. No other use of Sage may be used as justification for your answers. When you use Sage be sure to explain your input and show any relevant output (rather than just describing salient features). P_n is the vector space of polynomials with degree n or less, and $M_{m,n}$ is the vector space of $m \times n$ matrices.

1. Use the *definition* of a linear transformation to verify that T is a linear transformation. (15 points)

$$T: \mathbb{C}^{2} \to \mathbb{C}^{2} \quad T\left(\begin{bmatrix} a \\ b \end{bmatrix} \right) = \begin{bmatrix} 2a + b \\ a - b \end{bmatrix}$$

$$T\left(\underbrace{X} + \underbrace{Y} \right) = T\left(\begin{bmatrix} a_{1} \\ b_{1} \end{bmatrix} + \begin{bmatrix} a_{2} \\ b_{2} \end{bmatrix} \right) = T\left(\begin{bmatrix} a_{1} + a_{2} \\ b_{1} + b_{2} \end{bmatrix} \right) = \begin{bmatrix} 2(a_{1} + a_{2}) - (b_{1} + b_{2}) \end{bmatrix}$$

$$= \begin{bmatrix} (2a_{1} + b_{1}) + (2a_{2} + b_{2}) \\ (a_{1} - b_{1}) + (a_{2} - b_{2}) \end{bmatrix} = \begin{bmatrix} 2a_{1} + b_{1} \\ a_{2} - b_{2} \end{bmatrix} = T(\underbrace{X}) + T(\underbrace{Y})$$

$$E = \begin{bmatrix} (2a_{1} + b_{1}) + (a_{2} - b_{2}) \\ (a_{1} - b_{1}) + (a_{2} - b_{2}) \end{bmatrix} = T\left(\begin{bmatrix} a_{1} \\ a_{2} - b_{2} \end{bmatrix} \right) = T(\underbrace{X}) + T(\underbrace{Y})$$

$$E = \begin{bmatrix} a_{1} (2a_{1} + b_{1}) \\ (a_{1} - b_{1}) + (a_{2} - b_{2}) \end{bmatrix} = T\left(\begin{bmatrix} a_{2} \\ a_{2} - b_{2} \end{bmatrix} \right) = T(\underbrace{X}) + T(\underbrace{Y})$$

$$E = \begin{bmatrix} a_{1} (2a_{2} + b) \\ a_{2} - b_{2} \end{bmatrix} = T\left(\begin{bmatrix} a_{2} \\ b_{2} \end{bmatrix} \right) = T\left(\begin{bmatrix} a_{2} \\ a_{2} - b_{2} \end{bmatrix} \right) = T(\underbrace{X}) + T(\underbrace{Y})$$

$$E = \begin{bmatrix} a_{1} (2a_{2} + b) \\ a_{2} - a_{2} - b_{2} \end{bmatrix} = a = T(\underbrace{X})$$

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2. Find a basis for the range of T, $\mathcal{R}(T)$. (20 points)

$$T: \mathbb{C}^{3} \rightarrow P_{2} \qquad T\left(\begin{bmatrix}a\\b\\c\end{bmatrix}\right) = (a-2b-c) + (2a+b+3c)x + (3a+3c)x^{2}$$

Use a basis of \mathbb{C}^{3} ($\mathcal{I} e_{1}, e_{2}, e_{3}e_{3}$) and there $SSRT$ to
get a spanning set:
 $T(e_{1}) = 1 + 2x + 3x^{2}, T(e_{2}) = -2 + x, T(e_{3}) = -1 + 3x + 3x^{2}$
Then $R(T) = \langle \mathcal{I} + 2x + 3x^{2}, -2 + x, -1 + 3x + 3x^{2} + \rangle$
Then $R(T) = \langle \mathcal{I} + 2x + 3x^{2}, -2 + x, -1 + 3x + 3x^{2} + \rangle$
BUT this set is not invary independent. Note: the third
BUT this set is not invary independent. Note: the third
 $Polynomial$ is the sum of the first two. So revolve it.
 $Polynomial$ is $\mathcal{I} = \langle \mathcal{I} + 2x + 3x^{2}, -2 + x \rangle$

3. Consider the linear transformation S. (35 points)
S:
$$M_{1,3} \rightarrow P_2$$
 $S([a \ b \ c]) = (2a + 7b + 6c) + (a + 4b + 4c)x + (-b - c)x^2$
(a) Demonstrate that S is invertible.
 $\begin{bmatrix} a \ b \ c \end{bmatrix} \in K(S)$ if a,b,c is a soluthan do a holonogeneas system :
 $\begin{bmatrix} 2 & 76 \\ 1 & 44 \\ 0 & -1 - 1 \end{bmatrix}$ $EREF$ So $K(S) = 707$; $n(S) = 0 \pm S$ injective
 $r(S) + n(S) = dim (M_{1S}) = 1 \cdot 3 = 3$
 $\Rightarrow r(S) = 3$, which equads $dim (P_2) = 3$
 $cuelledicat marked$ So S is Surjectile.
(b) Find a formula for $S^{-1}: P_2 \rightarrow M_{1,3}$.
A basis for P_2 is 71 , x, x^2 (. Preimsges ?
 $S^{-1}(1) \Rightarrow$ solve system $\begin{bmatrix} 27 & 6 \\ 1 & 4 \\ 0 & -1 - 1 \end{bmatrix}$ $\stackrel{\text{PEEF}}{\Longrightarrow} \begin{bmatrix} 1 \\ -3 \end{bmatrix} \begin{bmatrix} 0 \\ -1 \end{bmatrix} = 5^{-1}(1) = 5^{-1}(1) = 1 \cdot 2 = 1 + 5^{-1}(1) = 5^{-1}(1) = 1 \cdot 2 = 1 + 5^{-1}(1) = 5^{-1}(1) = 5^{-1}(1) + 5^{-1}(1) = 5^{-1}(1) + 5^{-1}(1) = 5^{-1}(1) = 5^{-1}(1) = 5^{-1}(1) + 5^{-1}(1) = 5^{-1}(1) = 5^{-1}(1) = 5^{-1}(1) + 5^{-1}(2) = 4[6 - 1 - 1] + 5[1 - 22] + c[4 - 21]$
 $= \begin{bmatrix} 0 \ a \ -a \end{bmatrix} + \begin{bmatrix} b - 2b \ 2b \end{bmatrix} + \begin{bmatrix} 4c \ -2c \ c \end{bmatrix}$

(c) Compute the composition $S^{-1} \circ S$ and explain why this is a partial check on your work above. $(S^{-1} \circ S)([a b c]) = S^{-1}(S([a b c])) = S^{-1}((2a+7b+6c) + (a+4b+4c)X + (-b-c)X^{2}))$ $= [a+4b+4c+4(-b-c) \quad 2a+7b+6c-2(a+4b+4c)-2(-b-c) - (2a+7b+6c)+2(a+4b+4c) + (-b-c)] + (-b-c)]$ Caveful! $= [a b c] \quad So \quad S^{-1} \circ S = I_{M_{15}}, as capacital A full check would check <math>S \circ S^{-1} = I_{P_{2}}$ 4. The linear transformation R is not injective (you may assume this). Find two different vectors, \mathbf{x} and \mathbf{y} , such that $R(\mathbf{x}) = R(\mathbf{y})$. (15 points)

$$R: \mathbb{C}^{4} \rightarrow P_{3} \qquad R\left(\begin{bmatrix}a\\b\\c\\d\end{bmatrix}\right) = (b+c-2d) + (-a+3c+5d)x + (2b+3c-3d)x^{2} + (4b+8c-4d)x^{3}$$
By Theorem KILT, the leaved will not be third. Find this first:

$$0 + 0K + 0X^{2} + 0X^{3} = Q = R\left(\begin{bmatrix}a\\b\\c\\d\end{bmatrix}\right) \qquad |eads to a homsenous system w| coefficient notices, and the subsenous system of coefficient notices, b = 3 solution. C = -1
$$O = 1 + \frac{-2}{0} = R\left(\begin{bmatrix}a\\b\\c\\d\end{bmatrix}\right) \qquad PREF = \begin{bmatrix}0 & 0 & 0 & -2\\0 & 0 & 0 & 3\\0 & 0 & 0 & 1\\0 & 0 & 0 & 0\end{bmatrix} \qquad b = 3 solution.$$

$$S_{D} = R\left(\begin{bmatrix}z\\c\\d\\d\\d\end{bmatrix}\right) = 0 + 0X + 0X^{2} + 0X^{3} = R\left(\begin{bmatrix}c\\d\\d\\d\\d\\d\end{bmatrix}\right) \qquad f_{A} \qquad (27728 + 1)$$$$

5. Suppose that $T: U \to V$ and $S: U \to V$ are linear transformations which agree on a basis of U. That is, for some basis $B = {\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \ldots, \mathbf{u}_n}$ of $U, T(\mathbf{u}_i) = S(\mathbf{u}_i)$ for $1 \le i \le n$. Prove that T and S are equal functions. (15 points)

$$T = S \quad \text{means} \quad T(\underline{u}) = S(\underline{u}) \quad for \quad every \quad \underline{u} \in U$$

$$T(\underline{u}) = T(a, \underline{u}_1 + a_2, \underline{u}_2 + \dots + a_n, \underline{u}_n) \quad B \quad spans \quad U$$

$$= a, T(\underline{u}_1) + a_2 T(\underline{u}_2) + \dots + a_n T(\underline{u}_n) \quad LTLC$$

$$= a, \quad S(\underline{u}_1) + a_2 S(\underline{u}_2) + \dots + a_n S(\underline{u}_n) \quad Hyperflexis$$

$$= S(\underline{u}_1) \quad LTLC$$

$$= S(\underline{u})$$