Name: Key

Show all of your work and explain your answers fully. There is a total of 100 possible points.

Partial credit is proportional to the quality of your explanation. You may use Sage to row-reduce matrices. No other use of Sage may be used as justification for your answers, unless explicitly suggested in the problem's statement. When you use Sage be sure to explain your input and show any relevant output (rather than just describing salient features).

1. Consider the function $T: \mathbb{C}^2 \to \mathbb{C}^2$ below. (35 points)

$$T\left(\begin{bmatrix}a\\b\end{bmatrix}\right) = \begin{bmatrix}2a-b\\a+3b\end{bmatrix}$$

(a) Prove that T is a linear transformation.

By the definition,

$$T(X+y) = T\left(\begin{bmatrix}a_{1}\\b_{1}\end{bmatrix} + \begin{bmatrix}a_{2}\\b_{2}\end{bmatrix}\right) = T\left(\begin{bmatrix}a_{1}+a_{2}\\b_{1}+b_{2}\end{bmatrix}\right) = \begin{bmatrix}2(a_{1}+a_{2}) - (b_{1}+b_{2})\\a_{1}+a_{2}+3(b_{1}+b_{2})\end{bmatrix}$$

$$= \begin{bmatrix}(2a_{1}-b_{1}]\\(a_{1}+3b_{1}) + (2a_{2}-b_{2})\\(a_{1}+3b_{1}) + (a_{2}+3b_{2})\end{bmatrix} = \begin{bmatrix}2a_{1}-b_{1}\\a_{1}+3b_{1}\end{bmatrix} + \begin{bmatrix}2a_{2}-b_{2}\\a_{2}+3b_{2}\end{bmatrix} = T(X) + T(Y)$$

$$T(XX) = T(X\begin{bmatrix}a\\b\end{bmatrix}) = T\left(\begin{bmatrix}aA\\b\end{bmatrix}\right) = T\left(\begin{bmatrix}aA\\b\end{bmatrix}\right) = \begin{bmatrix}2(AA) - aAb\\a(A+3(b))\end{bmatrix} = \begin{bmatrix}a(2a-b)\\a(A+3b)\end{bmatrix} = aT(X)$$

$$\frac{OR}{a+3b} = T\left(\begin{bmatrix}a\\b\end{bmatrix}\right) = \begin{bmatrix}2a-b\\a+3b\end{bmatrix} = \begin{bmatrix}2-1\\b\end{bmatrix}\begin{bmatrix}a\\b\end{bmatrix}$$

$$\stackrel{i}{\Rightarrow} a \quad \text{(near Hauseformation by Theorem MBLT.}$$

(b) Is T injective? Why or why not?
To employ Theorem KILT, check the kernel of T

$$T(\begin{bmatrix} a\\ b\end{bmatrix}) = Q = \begin{bmatrix} 0\\ 0 \end{bmatrix}$$

 $\begin{bmatrix} 2a - b\\ a + 3b \end{bmatrix} = \begin{bmatrix} 0\\ 0 \end{bmatrix}$ leads to holdwisenous
 $a + 3b = \begin{bmatrix} 0\\ 0 \end{bmatrix}$ leads to holdwisenous
 $a + 3b = \begin{bmatrix} 0\\ 0 \end{bmatrix}$ leads to holdwisenous
 $a + 3b = \begin{bmatrix} 0\\ 0 \end{bmatrix} = \begin{bmatrix} 0\\ 0 \end{bmatrix}$ leads to holdwisenous
 $a + 3b = \begin{bmatrix} 0\\ 0 \end{bmatrix} = \begin{bmatrix} 0\\ 0 \end{bmatrix}$ leads to holdwisenous
 $a + 3b = \begin{bmatrix} 0\\ 0 \end{bmatrix} = \begin{bmatrix}$

2. Consider the linear transformation $T: S_{22} \to P_2$ defined below, where S_{22} is the vector space of 2×2 symmetric matrices, and P_2 is the vector space of polynomials of degree at most 2. (35 points)

$$T\left(\begin{bmatrix}a & b\\ b & c\end{bmatrix}\right) = (3a + b + 5c) + (2a + b + 4c)x + (-3a + 4b + 5c)x^{2}$$
(a) Compute the kernel of T, $\mathcal{K}(T)$. System $\omega|_{-3} = 45$

$$T\left(\begin{bmatrix}a & b\\ b & c\end{bmatrix}\right) = Q = 0 + 0\mathcal{K} + 0x^{2} \quad \text{coeff mstark} \quad \begin{bmatrix}3 & 15 \\ 2 & 14 \\ -3 & 45\end{bmatrix} \quad \begin{bmatrix}4 & 0 & 0 & 2 \\ 0 & 0 & 0\end{bmatrix}$$

$$C \quad \text{is five, } a = -C$$

$$b = -2C$$

$$kor \quad (T) = \left\{\begin{bmatrix}-c & -2c \\ -2c & c\end{bmatrix}\right] \quad C \in C\left\{\left\{= \left\{\left\{\int_{-2}^{-1} & -2 \\ -2 & 1\end{bmatrix}\right\}\right\}\right\} \\ = \left\{c \begin{bmatrix}-1 & -2 \\ -2 & 1\end{bmatrix}\right\} \quad C \in C\left\{= \left\{\int_{-2}^{-1} & -2 \\ -2 & 1\end{bmatrix}\right\}\right\}$$
(b) Compute the range of T, $\mathcal{R}(T)$. A basis of the dumain is
$$\left\{\begin{bmatrix}1007 \\ 007 \\ 007 \end{bmatrix}, \begin{bmatrix}007 \\ 00$$

(c) The rank and nullity of T obey a basic relationship. Say what this relationship is, and verify it for T. $r(T) + n(T) = din (domain) = din (S_{22}) = 3$ $r(T) + n(T) = din (domain) = din (S_{22}) = 3$ $r(T) + n(T) = din (domain) = din (S_{22}) = 3$

 3. For the linear transformation $R: M_{22} \to \mathbb{C}^3$ find a specific element of the codomain with an empty pre-image, demonstrating that R is not surjective. (M_{22} is the vector space of 2×2 matrices.) (15 points)

$$R\left(\begin{bmatrix}a & b\\c & d\end{bmatrix}\right) = \begin{bmatrix}a+2c+2d\\a-b+3c+d\\b-c+d\end{bmatrix} \quad \text{We desire } \begin{bmatrix}y\\y\\z\end{bmatrix} \text{ so that } R\left(\begin{bmatrix}a & b\\c & d\end{bmatrix}\right) = \begin{bmatrix}y\\y\\z\end{bmatrix} \text{ has no solution} \\ \begin{bmatrix}1 & 0 & 2 & 2\\z\end{bmatrix} \\ x \text{ solution} \\ x \text$$

4. Suppose that $S: U \to V$ and $T: V \to W$ are linear transformations and each is injective. Prove that their composition, $T \circ S$ is invertible. (15 points) injective

Suppose

$$T(S(u_1)) = T(S(u_2))$$

 $\Rightarrow S(u_1) = S(u_2)$ since T injecture
 $\Rightarrow u_1 = u_2$ since S injecture.
Which Says $T \circ S$ is injecture.

Suppose

$$\chi \in \text{Kev}(T \circ S)$$

 $\Rightarrow T(S(\underline{x})) = Q$
 $\Rightarrow S(\underline{x}) = 0 \quad \text{since} \quad \text{Kev}T = \frac{1}{2}Q^{4}$
 $\Rightarrow \underline{x} = Q \quad \text{since} \quad \text{Kev}S = \frac{1}{2}Q^{4}$
 $\Rightarrow \text{Kev}(T \circ S) = \frac{1}{2}Q^{4}$
 $\Rightarrow \text{Huns} T \circ S \quad \text{is injective by Theorem KIZT}$